

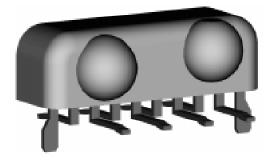
# **IBM31T1100A** Integrated Infrared Transceiver Module

## Highlights

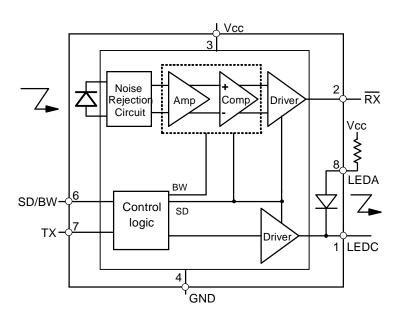
- IrDA 1.1, HP-SIR and Sharp ASK compliant
- Supports IrDA data rates up to 4 Mbps
- Low profile (height = 5.6 mm max.)
- Minimum external components
- On-chip LED protection circuit
- Low power consumption
- 5 V Supply Voltage
- Complete differential receiver design
- · Ambient light and noise rejection circuitry
- Shutdown pin for power management
- Programmable bandwidth control
- Compatible with all major Super I/Os

## **General Description**

The IBM31T1100A is a multi-mode integrated infrared (IR) transceiver module for data communication systems. The transceiver supports IrDA speeds up to 4 Mbps, HP-SIR and Sharp ASK modes. Integrated into this tiny package is a photodiode, LED and analog transceiver ASIC to provide a total solution in a single package. A current limiting resistor in series with the LED and a Vcc bypass capacitor are the only external components required to implement a complete transceiver.

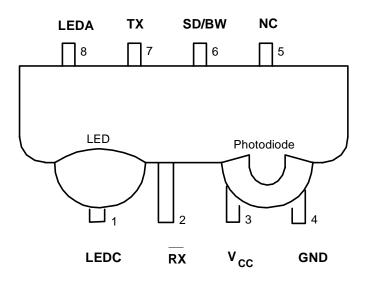


Package



Block Diagram

# **Pin Assignments and Descriptions**



Pin	Pin Name	Description	I/O	Active
1	LEDC	Indicates the state of the internal LED cathode. Normally not connected.	0	Low
2	RX	Indicates received serial data. It is a push-pull CMOS driver capable of driving a standard CMOS or TTL load. No external pull-up or pull-down resistor is required. May switch indeterminately when the IBM31T1100A is transmitting.	0	Low
3	V <sub>cc</sub>	Connect to $+5$ V power supply. Place a 1.0-10 $\mu$ F ceramic bypass capacitor as close as possible to this pin.		
4	GND	Connect to ground of the power supply. A solid ground plane is recommended for proper operation.		
5	NC	This pin is reserved for special application use only. No signal should be connected to this pin.		
6	SD/BW	This CMOS input is used to put the IBM31T1100A in shutdown mode. Nominal supply current draw in this mode is $35 \mu$ A versus 5 mA in normal mode. Together with the TX input, this pin also sets the receiver bandwidth. If TX is low when SD/BW transitions from high to low, the receiver bandwidth is optimized for operation up to 1.2 Mbps. If TX is high when SD/BW transitions from high to low, the receiver bandwidth is optimized for operation at 4 Mbps.	Ι	High
7	ТХ	Used to transmit serial data when SD/BW is low. This CMOS input controls the LED driver. An on-chip protection circuit disables the LED driver if TX is high for more than 60 µsec. This pin is also used to program the bandwidth of the receiver. See SD/BW pin description.	Ι	High
8	LEDA	Connect this input to Vcc through a resistor to set the proper LED current. Add an external LED in series to increase output intensity if required.	Ι	
	Guide Pins (not shown above)	Two through-hole guide pins provide mechanical stability during board mounting. They also improve heat conduction when the part is in operation.		

## NOTE: The IBM31T1100A is pin and plug compatible with the Temic TFDS6000D.

#### IBM31T1100A

# **Electrical and Timing Specifications**

## Absolute Maximum Ratings

Symbol	Parameter	Min	Тур	Max	Unit	Condition
Vcc	Supply Voltage Range	- 0.5		6	V	
PD	Power Dissipation			450	mW	
TJ	Junction Temperature			125	°C	
	Storage Temperature Range	- 25		85	°C	
	Soldering Temperature			240	°C	See application notes
I <sub>LED</sub>	LED Current			0.8	А	<2 µs, t <sub>on</sub> <10%
	Voltage at Any Pin	- 0.5		V <sub>cc</sub> + 0.5	V	

#### **Recommended Operating Conditions**

Symbol	Parameter	Min	Тур	Max	Unit	Condition
V <sub>CC</sub>	Supply Voltage	4.5	5	5.5	V	
T <sub>A</sub>	Operating Temperature Range	0		70	°C	

# DC Electrical Characteristics

 $T_A\!=\!0$  - 70 °C,  $V_{CC}\!=\!5$  V  $\pm\,10$  %, unless otherwise specified

Symbol	Parameter	Min	Тур	Max	Unit	Condition
Icc	Dynamic Supply Current		5	7	mA	SD = 0 V
I <sub>CC</sub>	Standby Supply Current		35	100	uA	$SD = V_{CC} - 0.5, SC = NC$
I <sub>LED</sub>	Repetitive Pulsed LED Current			0.55	А	$< 60 \ \mu s, t_{on} \le 25 \ \%$
Vol	$\overline{\text{RX}}$ Output Voltage Low @ $I_{OL} = 2.5 \text{ mA}$		0.3	0.5	V	
V <sub>OH</sub>	$\overrightarrow{RX}$ Output Voltage High @ -I <sub>OH</sub> = 2.5 mA	V <sub>CC</sub> -0.5			V	
V <sub>IL</sub>	Input Voltage Low (TX, SD/BW)	0		0.8	V	
V <sub>IH</sub>	Input Voltage High (TX)	3.0			V	
V <sub>IH</sub>	Input Voltage High (SD/BW)	V <sub>CC</sub> -0.5			V	
IL	Input Leakage Current	-10		+10	uA	
CI	Input Capacitance			5	pF	

#### AC Electrical Characteristics

#### $T_A\!=\!0$ - 70 °C, $V_{CC}\!=\!5$ V $\pm$ 10 %, unless otherwise specified

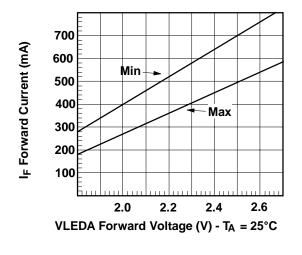
Symbol	Parameter	Min	Тур	Max	Unit	Condition
t <sub>R</sub>	RX Rise Time	10		40	ns	$R_{LED}$ = 2.0 K $\Omega$ , C = 50 pF
t <sub>F</sub>	RX Fall Time	10		40	ns	$R_{LED} \!=\! 2.0 \text{ K}\Omega, C \!=\! 50 \text{ pF}$
ts	TX Setup Time to SD/BW Low	200			ns	
t <sub>H</sub>	TX Hold Time from SD/BW Low	200			ns	
$t_{\rm PW}$	RX Pulse Width	0.8		20	us	9.6 kbps
$t_{\rm PW}$	RX Pulse Width	100		500	ns	1.2 Mbps
$t_{\rm PW}$	RX Pulse Width	60		165	ns	4 Mbps
$t_{\rm PW}$	RX Pulse Width	185		290	ns	4 Mbps double pulse
t <sub>D</sub>	Output Delay @ $E_e = 40 \text{ mW/cm}^2$		1	2	us	≤ 1.2 Mbps
$t_{\rm L}$	Latency			120	us	
t <sub>RXEN</sub>	RX Valid After Shutdown			60	us	
t <sub>DIS_LED</sub>	LEDC Inactive After TX High			60	us	

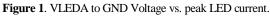
## **Optical Characteristics**

 $T_A$  = 0 - 70 °C,  $V_{CC}$  = 5 V ± 10%, unless otherwise specified

Symbol	Parameter	Min	Тур	Max	Unit	Condition
E <sub>emin</sub>	Minimum Detection Irradiance (SIR mode)		0.025	0.035	Wm <sup>-2</sup>	9.6 - 115 kbps
E <sub>emin</sub>	Minimum Detection Irradiance		0.035	0.05	Wm <sup>-2</sup>	1.2 Mbps
E <sub>emin</sub>	Minimum Detection Irradiance		0.07	0.08	Wm <sup>-2</sup>	4 Mbps
E <sub>emax</sub>	Maximum Detection Irradiance	5000			Wm <sup>-2</sup>	All speeds
		100	140	320(1)	mW/sr	Tx = High, SD = Low, $R_{LED}$ = 5.6 $\Omega$
Ie	Output Radiant Intensity					V <sub>CC</sub> =5.0, α=0 °, α=±15 °, T <sub>A</sub> =25 °C
				0.4	uW/sr	Tx=Low or SD=High, $R_{LED}$ =5.6 $\Omega$
						V <sub>CC</sub> =5.0, α=0 °, α=±15 °, T <sub>A</sub> =25 °C
α	Output Radiant Intensity Half Angle		±24		0	
$\lambda_{P}$	Peak Wavelength	880		900	nm	
	Optical Overshoot			25	%	

1. Maximum intensity specified for class 1 operation of IEC 825-1





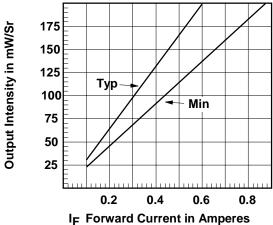


Figure 3. Output Intensity vs. Current

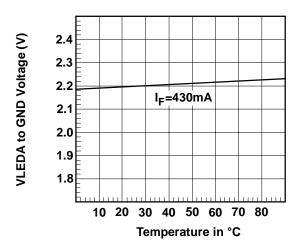


Figure 5. VLEDA to GND Voltage vs. Temperature.

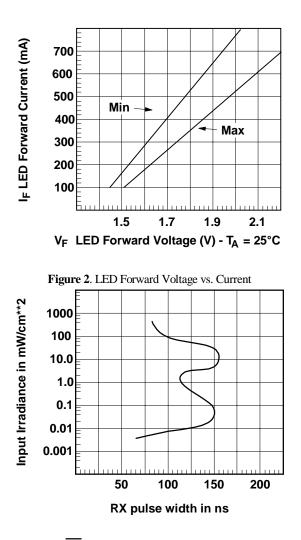


Figure 4. RX pulse width vs. Irradiance - 4 Mbps mode.

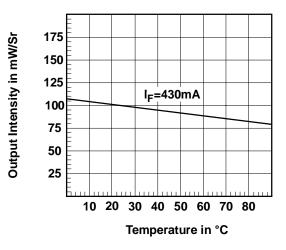


Figure 6. Output Intensity vs. Temperature

## **Timing Diagrams**

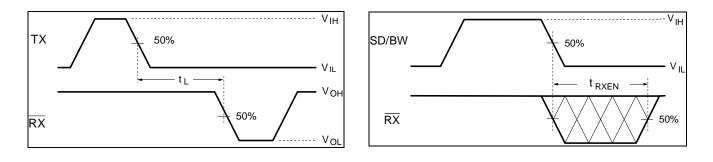


Figure 7. Latency Timing

Figure 8. RX valid after Shutdown.

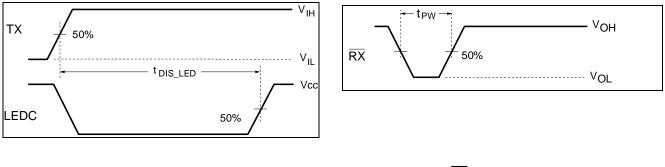
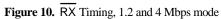
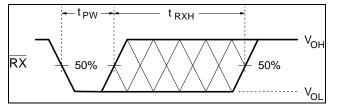
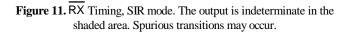
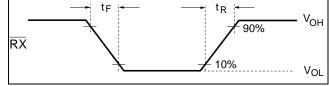


Figure 9. LED Protection Timing









**Figure 12.**  $\overrightarrow{\mathsf{RX}}$  Rise and Fall timing measurements.

## Programming the Receiver Bandwidth

The IBM31T1100A powers on with the upper limit of the receiver bandwidth set to 1.2 Mbps operation. To set the bandwidth for operation at 4 Mbps, apply timings as shown in Figure 14 to the SD/BW and the TX inputs. Note that the internal LED driver is disabled when SD/BW is active and is not enabled until the next rising edge of TX. This ensures that the LED(s) will not be active during bandwidth adjustment. It is recommended that the SD/BW pin be connected to GND if bandwidth adjustment and shutdown mode are not used.

To switch the IBM31T1100A from the default state to 4 Mbps and vice versa, the programming specifications are as follows:

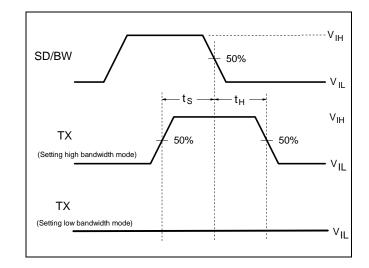


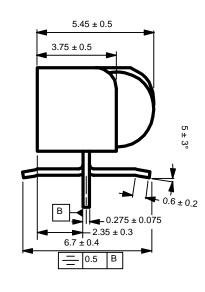
Figure 13. Bandwidth Programming

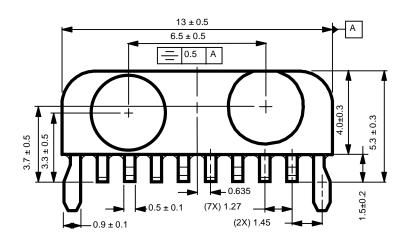
#### Setting the receiver to 9.6 kbps-to-1.2 Mbps mode

- 1. Set the SD/BW input to logic high.
- 2. Ensure that the TX input is at logic low. Wait  $t_S \ge 200$  ns.
- Set the SD/BW to logic low. (This high-to-low transition latches the state of TX, which determines the receiver bandwidth.)
- 4. Ensure that the TX input remains low for  $t_H \ge 200$  ns. The receiver is now in low bandwidth mode, which is the optimal setting for data rates from 9.6 kbps to 1.2 Mbps.

#### Setting the receiver to 4 Mbps mode

- 1. Set the SD/BW input to logic high.
- 2. Set the TX input to logic high. Wait  $t_S \ge 200$  ns.
- Set the SD/BW to logic low. (This high-to-low transition latches the state of TX, which determines the receiver bandwidth.)
- 4. After waiting  $t_H \ge 200$  ns, set the TX input to logic low. The receiver is now in high bandwidth mode, the optimal setting for 4 Mbps operation.





#### Dimensions in mm.

## **Package Dimensions**

#### **Revision History**

The following changes have been made in the specifications from the IBM31T1100 data sheet.

- 1. Improved Irradiance values have been updated.
- 2. LED protection circuit has been added.
- 3. The  $\overline{\mathsf{RX}}$  rise time specification is 40 ns instead of 35 ns.
- 4. 200K internal pull-down resistor has been removed from the SD/BW pin.
- 5. Output Intensity and  $\overline{\mathsf{RX}}$  pulse width graphs have been updated.

## **Ordering Information**

Order Part Number IBM31T1100A

**Qty/Reel** 750 Pieces

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IBM Microelectronics Division 1580 Route 52, Bldg. 504 Hopewell Junction, NY 12533-6531

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