

# Micropower Single-Supply Rail-to-Rail Input/Output Op Amps

# OP191/OP291/OP491

#### FEATURES

Single-Supply Operation: 2.7 V to 12 V Wide Input Voltage Range Rail-to-Rail Output Swing Low Supply Current: 300 μA/Amp Wide Bandwidth: 3 MHz Slew Rate: 0.5 V/μs Low Offset Voltage: 700 μV No Phase Reversal

#### **APPLICATIONS**

Industrial Process Control Battery Powered Instrumentation Power Supply Control and Protection Telecom Remote Sensors Low Voltage Strain Gage Amplifiers DAC Output Amplifier

#### **GENERAL DESCRIPTION**

The OP191, OP291 and OP491 are single, dual and quad micropower, single-supply, 3 MHz bandwidth amplifiers featuring rail-to-rail inputs and outputs. All are guaranteed to operate from a 3 volt single supply as well as  $\pm 5$  volt dual supplies.

Fabricated on Analog Devices' CBCMOS process, the OP191 family has a unique input stage that allows the input voltage to safely extend 10 volts beyond either supply without any phase inversion or latch-up. The output voltage swings to within millivolts of the supplies and continues to sink or source current all the way to the supplies.

Applications for these amplifiers include portable telecom equipment, power supply control and protection, and interface for transducers with wide output ranges. Sensors requiring a rail-to-rail input amplifier include Hall effect, piezo electric, and resistive transducers.

The ability to swing rail-to-rail at both the input and output enables designers to build multistage filters in single-supply systems and maintain high signal-to-noise ratios.

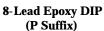
The OP191/OP291/OP491 are specified over the extended industrial (-40°C to +125°C) temperature range. The OP191 single and OP291 dual amplifiers are available in 8-pin plastic DIPs and SO surface mount packages. The OP491 quad is available in 14-pin DIPs and narrow 14-pin SO packages. Consult factory for OP491 TSSOP availability.

#### REV.0

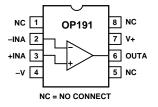
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#### **OP191/OP291/OP491 PIN CONFIGURATIONS**

8-Lead Narrow-Body SO (S Suffix)

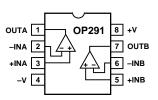






#### 8-Lead Narrow-Body SO (S Suffix)

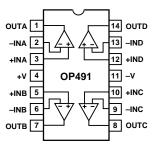




8-Lead Epoxy DIP

(P Suffix)

14-Lead Epoxy DIP (P Suffix)









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# OP191/OP291/OP491-SPECIFICATIONS

# **ELECTRICAL SPECIFICATIONS** (@ $V_s = +3.0 V$ , $V_{CM} = 0.1 V$ , $V_0 = 1.4 V$ , $T_A = +25^{\circ}C$ unless otherwise noted)

Parameter	Symbol	Conditions	Min	Тур	Max	Units
INPUT CHARACTERISTICS Offset Voltage OP191G	V <sub>OS</sub>			80	500	μV
onset voltage of ford	• US	$-40 \leq T_A \leq +125^{\circ}C$		00	1	mV
OP291/OP491G	V <sub>OS</sub>	A		80	700	μV
		$-40 \leq T_A \leq +125^\circ C$			1.25	mV
Input Bias Current	I <sub>B</sub>			30	50	nA
	Ŧ	$-40 \leq T_A \leq +125^\circ C$		0.1	70	nA
Input Offset Current	I <sub>OS</sub>	$-40 \le T_A \le +125^{\circ}C$		0.1	8 16	nA nA
Input Voltage Range		$-40 \le 1_A \le +123$ C	0		3	V
Common-Mode Rejection Ratio	CMRR	$V_{CM} = 0 V$ to 2.9 V	70	90	0	dB
		$-40 \le T_A \le +125^{\circ}C$	65	87		dB
Large Signal Voltage Gain	$A_{VO}$	$R_L = 10 \text{ k}\Omega$ , $V_O = 0.3 \text{ V}$ to 2.7 V	25	70		V/mV
		$-40 \le T_A \le +125^\circ C$		50		V/mV
Offset Voltage Drift	$\Delta V_{OS} / \Delta T$			1.1		μV/°C
Bias Current Drift	$\Delta I_{B}/\Delta T$			100		pA/°C
Offset Current Drift	$\Delta I_{OS} / \Delta T$			20		pA/°C
OUTPUT CHARACTERISTICS						
Output Voltage High	V <sub>OH</sub>	$R_{\rm L} = 100 \ \rm k\Omega$ to GND	2.95	2.99		V
		-40°C to +125°C	2.90	2.98		V
		$R_{\rm L} = 2 \ {\rm k}\Omega$ to GND	2.8	2.9		V
	<b>.</b>	$-40^{\circ}$ C to $+125^{\circ}$ C	2.70	2.8	10	V
Output Voltage Low	V <sub>OL</sub>	$R_L = 100 \text{ k}\Omega \text{ to } V +$		4.5	10	mV
		$-40^{\circ}$ C to $+125^{\circ}$ C		40	35 75	mV mV
		$R_{\rm L} = 2 \ k\Omega \ \text{to} \ V + -40^{\circ}C \ \text{to} \ +125^{\circ}C$		40	75 130	mV
Short Circuit Limit	I <sub>SC</sub>	Sink/Source	±8.75	$\pm 13.5$	130	mA
Short Circuit Linit	ISC	$-40^{\circ}$ C to $+125^{\circ}$ C	$\pm 6.0$	$\pm 10.5$ $\pm 10.5$		mA
Open Loop Impedance	$\mathbf{Z}_{\mathrm{OUT}}$	$f = 1 \text{ MHz}, A_V = 1$		200		Ω
POWER SUPPLY						
Power Supply Rejection Ratio	PSRR	$V_{\rm S} = 2.7 \text{ V}$ to 12 V	80	110		dB
rower supply nejection reado	1 SIGN	$-40^{\circ}C \le T_A \le +125^{\circ}C$	75	110		dB
Supply Current/Amplifier	I <sub>SY</sub>	$V_0 = 0 V$		200	350	μA
r r	51	$-40^{\circ}C \le T_A \le +125^{\circ}C$		330	480	μA
DYNAMIC PERFORMANCE						
Slew Rate	+SR	$R_{L} = 10 \text{ k}\Omega$		0.4		V/µs
Slew Rate	-SR	$R_{\rm L} = 10 \text{ k}\Omega$ $R_{\rm L} = 10 \text{ k}\Omega$		0.4 0.4		V/µs V/µs
Full-Power Bandwidth	-SR BW <sub>P</sub>	1% Distortion		0.4 1.2		kHz
Settling Time	t <sub>s</sub>	To 0.01%		22		μs
Gain Bandwidth Product	GBP			3		MHz
Phase Margin	$\theta_{O}$			45		Degrees
Channel Separation	ČŠ	$f = 1 \text{ kHz}, R_L = 10 \text{ k}\Omega$		145		dB
NOISE PERFORMANCE						
Voltage Noise	e n-n	0.1 Hz to 10 Hz		2		μV p-p
Voltage Noise Density	e <sub>n</sub> p-p e <sub>n</sub>	f = 1  kHz		2 35		$nV/\sqrt{Hz}$
Current Noise Density	i <sub>n</sub>			0.8		$pA/\sqrt{Hz}$
Current Poise Delibity	'n			0.0		Provinz

Specifications subject to change without notice.

# **ELECTRICAL SPECIFICATIONS** (@ $V_s = +5.0 V$ , $V_{CM} = 0.1 V$ , $V_0 = 1.4 V$ , $T_A = +25^{\circ}C$ unless otherwise noted)

Parameter	Symbol	Conditions	Min	Тур	Max	Units
INPUT CHARACTERISTICS Offset Voltage OP191	V <sub>OS</sub>	$-40 \le T_A \le +125^{\circ}C$		80	500 1.0	μV mV
OP291/OP491	V <sub>OS</sub>	$-40 \le T_A \le +125^{\circ}C$		80	700 1.25	μV mV
Input Bias Current	I <sub>B</sub>	$-40 \le T_A \le +125^{\circ}C$		30	50 60	nA nA
Input Offset Current	I <sub>OS</sub>	$-40 \le T_A \le +125^{\circ}C$		0.1	8 16	nA nA
Input Voltage Range Common-Mode Rejection Ratio	CMRR	$V_{CM} = 0 V \text{ to } 4.9 V$ $-40 \le T_A \le +125^{\circ}C$	0 70 65	93 90	5	V dB dB
Large Signal Voltage Gain	$A_{VO}$	$\begin{array}{l} \textbf{R}_{L}=10~\text{k}\Omega~\text{, }V_{O}=0.3~\text{V to }4.7~\text{V}\\ \textbf{-40}\leq T_{A}\leq+125^{\circ}\text{C} \end{array}$	25	70 50		V/mV V/mV
Offset Voltage Drift Bias Current Drift Offset Current Drift	$\Delta V_{OS}/\Delta T$ $\Delta I_B/\Delta T$ $\Delta I_{OS}/\Delta T$	$-40 \le T_A \le +125^{\circ}C$		1.1 100 20		μV/°C pA/°C pA/°C
OUTPUT CHARACTERISTICS Output Voltage High	V <sub>OH</sub>	$R_L = 100$ kΩ to GND -40°C to +125°C	4.95 4.90	4.99 4.98		V V
Output Voltage Low	V <sub>OL</sub>	$\begin{split} R_L &= 2 \ k\Omega \ to \ GND \\ -40^\circ C \ to \ +125^\circ C \\ R_L &= 100 \ k\Omega \ to \ V+ \\ -40^\circ C \ to \ +125^\circ C \\ R_L &= 2 \ k\Omega \ to \ V+ \end{split}$	4.8 4.65	4.85 4.75 4.5 40	10 35 75	V V mV mV mV
Short Circuit Limit	I <sub>SC</sub>	$-40^{\circ}$ C to $+125^{\circ}$ C Sink/Source $-40^{\circ}$ C to $+125^{\circ}$ C	$_{\pm 6.0}^{\pm 8.75}$	$^{\pm 13.5}_{\pm 10.5}$	155	mV mA mA
Open Loop Impedance	Z <sub>OUT</sub>	$f = 1$ MHz, $A_V = 1$	_ 010	200		Ω
POWER SUPPLY Power Supply Rejection Ratio	PSRR	$V_{\rm S} = 2.7 \text{ V to } 12 \text{ V}$	80	110		dB
Supply Current/Amplifier	I <sub>SY</sub>	$\begin{array}{l} -40 \leq T_{\rm A} \ \leq +125^{\circ}{\rm C} \\ V_{\rm O} = 0 \ V \\ -40 \leq T_{\rm A} \leq +125^{\circ}{\rm C} \end{array}$	75	110 220 350	400 500	dB μΑ μΑ
DYNAMIC PERFORMANCE Slew Rate Slew Rate Full-Power Bandwidth Settling Time Gain Bandwidth Product Phase Margin Channel Separation	+SR -SR BW <sub>P</sub> $t_S$ GBP $\theta_O$ CS	$R_{L} = 10 \text{ k}\Omega$ $R_{L} = 10 \text{ k}\Omega$ $1\% \text{ Distortion}$ $To 0.01\%$ $f = 1 \text{ kHz}, R_{L} = 10 \text{ k}\Omega$		0.4 0.4 1.2 22 3 45 145		V/µs V/µs kHz µs MHz Degrees dB
NOISE PERFORMANCE Voltage Noise Voltage Noise Density Current Noise Density	e <sub>n</sub> p-p e <sub>n</sub> i <sub>n</sub>	0.1 Hz to 10 Hz f = 1 kHz		2 35 0.8		µV p-p nV/√Hz pA/√Hz

NOTES

 $\pm 5$  V specifications are guaranteed by  $\pm 3$  V and  $\pm 5$  V testing. Specifications subject to change without notice.

### $\label{eq:Electrical specifications} \text{ELECTRICAL SPECIFICATIONS} \ (@V_0 = \pm 5.0 \ \text{V}, -4.9 \ \text{V} \le V_{\text{CM}} \le +4.9 \ \text{V}, \ \text{T}_{\text{A}} = +25^{\circ}\text{C} \ \text{unless otherwise noted})$

Parameter		Symbol	Conditions	Min	Тур	Max	Units
INPUT CHARACTI Offset Voltage	ERISTICS OP191	V <sub>OS</sub>			80	500	μV
	OP291/OP491	V <sub>OS</sub>	$-40 \le T_A \le +125^{\circ}C$ $-40 \le T_A \le +125^{\circ}C$		80	1 700 1.25	mV μV mV
Input Bias Current		I <sub>B</sub>	$-40 \le T_A \le +125^{\circ}C$		30	50 70	nA nA
Input Offset Curren		I <sub>OS</sub>	$-40 \le T_A \le +125^{\circ}C$		0.1	8 16	nA nA
Input Voltage Rang Common-Mode Re		CMR	$\begin{split} V_{CM} &= \pm 5 \ V \\ -40 \leq T_A \leq +125^\circ C \end{split}$	-5 75 67	100 97	+5	V dB dB
Large Signal Voltag	ge Gain	$A_{VO}$	$\label{eq:RL} \begin{split} R_L &= 10 \ \mathrm{k}\Omega, \ V_O = \pm 4.7 \ \mathrm{V}, \\ -40 &\leq T_A \leq +125^\circ \mathrm{C} \end{split}$	25	70 50		V/mV
Offset Voltage Drif Bias Current Drift Offset Current Drift		$\Delta V_{OS}/\Delta T$ $\Delta I_B/\Delta T$ $\Delta I_{OS}/\Delta T$			1.1 100 20		µV/°C pA/°C pA/°C
OUTPUT CHARAC Output Voltage Sw		Vo	RL = 100 kΩ to GND-40°C to +125°CRL = 2 kΩ to GND	$\pm 4.93 \\ \pm 4.90 \\ \pm 4.80 \\ \pm 4.65 $	$\pm 4.99 \\ \pm 4.98 \\ \pm 4.95 \\ \pm 4.75$		V V V V
Short Circuit Limit		I <sub>SC</sub>	$-40 \le T_A \le +125^{\circ}C$ Sink/Source $-40^{\circ}C \text{ to } +125^{\circ}C$	$^{\pm 4.65}_{\pm 8.75}$ $^{\pm 6}_{\pm 6}$	$_{\pm 16}^{\pm 13}$		w mA mA
Open Loop Impeda	ance	Z <sub>OUT</sub>	$f = 1 MHz, A_V = 1$		200		Ω
POWER SUPPLY Power Supply Reje	ction Ratio	PSRR	$V_{S} = \pm 5 V$ -40 \le T_{A} \le +125°C	80 70	110 100		dB dB
Supply Current/An	nplifier	I <sub>SY</sub>	$\begin{array}{l} V_{\rm O}=0~V\\ -40\leq T_{\rm A}\leq +125^{\circ}C \end{array}$		260 390	420 550	μΑ μΑ
DYNAMIC PERFOI Slew Rate Full-Power Bandwi Settling Time Gain Bandwidth Pr Phase Margin Channel Separation	idth roduct	$\pm$ SR BW <sub>P</sub> t <sub>S</sub> GBP $\theta_0$ CS	$R_{L} = 10 \text{ k}\Omega$ 1% Distortion To 0.01% f = 1  kHz		0.5 1.2 22 3 45 145		V/µs kHz µs MHz Degrees dB
NOISE PERFORMA Voltage Noise Voltage Noise Den Current Noise Den	sity	e <sub>n</sub> p-p e <sub>n</sub> i <sub>n</sub>	0.1 Hz to 10 Hz f = 1 kHz		2 35 0.8		µV p-p nV/√Hz pA/√Hz

Specifications subject to change without notice.

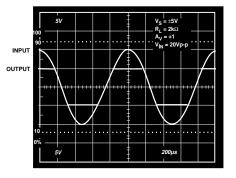


Figure 1. Input and Output with Inputs Overdriven by 5 V

Parameter	Symbol	Conditions	Limit	Units
Offset Voltage	V <sub>OS</sub>		±300	μV max
Input Bias Current	IB		50	nA max
Input Offset Current	I <sub>OS</sub>		8	nA
Input Voltage Range	V <sub>CM</sub>		V- to V+	V min
Common-Mode Rejection Ratio	CMRR	$V_{CM} = 0 V \text{ to } +2.9 V$	70	dB min
Power Supply Rejection Ratio	PSRR	V = 2.7 V  to  +12 V	80	dB min
Large Signal Voltage Gain	A <sub>VO</sub>	$R_L = 10 \ k\Omega$	50	V/mV min
Output Voltage High	V <sub>OH</sub>	$R_L = 2 k\Omega$ to GND	2.8	V min
Output Voltage Low	V <sub>OL</sub>	$R_L = 2 k\Omega$ to V+	75	mV max
Supply Current/Amplifier	I <sub>SY</sub>	$V_O = 0 V, R_L = \infty$	350	μA max

### WAFER TEST LIMITS (@ $V_S = +3.0 V$ , $V_{CM} = 0.1 V$ , $T_A = +25^{\circ}C$ unless otherwise noted)

#### NOTE

Electrical tests and wafer probe to the limits shown. Due to variations in assembly methods and normal yield loss, yield after packaging is not guaranteed for standard product dice. Consult factory to negotiate specifications based on dice lot qualifications through sample lot assembly and testing.

#### ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

Supply Voltage +16 V
Input VoltageGND to $V_{S}$ + 10 V
Differential Input Voltage7 V
Output Short-Circuit Duration to GND Indefinite
Storage Temperature Range
P, S, RU Packages $\dots \dots \dots$
Operating Temperature Range
OP191/OP291/OP491G40°C to +125°C
Junction Temperature Range
P, S, RU Packages65°C to +150°C
Lead Temperature Range (Soldering 60 sec) +300°C

Package Type	$\theta_{JA}^2$	$\theta_{JC}$	Units
8-Pin Plastic DIP (P)	103	43	°C/W
8-Pin SOIC (S)	158	43	°C/W
14-Pin Plastic DIP (P)	76	33	°C/W
14-Pin SOIC (S)	120	36	°C/W
14-Pin TSSOP (RU)	180	35	°C/W

#### ORDERING GUIDE

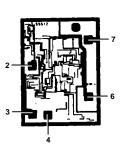
Model	Temperature Range	Package Description	Package Option
OP191GP	-40°C to +125°C	8-Pin Plastic DIP	N-8
OP191GS	-40°C to +125°C	8-Pin SOIC	SO-8
OP191GBC	+25°C	DICE	
OP291GP	-40°C to +125°C	8-Pin Plastic DIP	N-8
OP291GS	-40°C to +125°C	8-Pin SOIC	SO-8
OP291GBC	+25°C	DICE	
OP491GP	-40°C to +125°C	14-Pin Plastic DIP	N-14
OP491GS	-40°C to +125°C	14-Pin SOIC	SO-14
OP491HRU	-40°C to +125°C	14-Pin TSSOP	RU-14
OP491GBC	+25°C	DICE	

#### NOTES

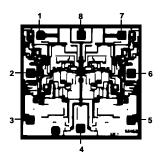
<sup>1</sup>Absolute maximum ratings apply to both DICE and packaged parts, unless otherwise noted.

 $^2\theta_{JA}$  is specified for the worst case conditions; i.e.,  $\theta_{JA}$  is specified for device in socket for P-DIP packages;  $\theta_{JA}$  is specified for device soldered in circuit board for TSSOP and SOIC packages.

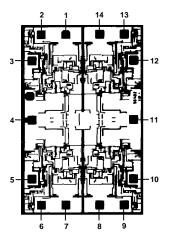
#### DICE CHARACTERISTICS



OP191 Die Size  $0.047 \times 0.066$  Inch, 3,102 Sq. Mils. Substrate (Die Backside) Is Connected to V+. Transistor Count, 74.

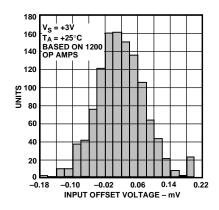


OP291 Die Size 0.070 × 0.070 Inch, 4,900 Sq. Mils. Substrate (Die Backside) Is Connected to V+. Transistor Count, 146



OP491 Die Size  $0.070 \times 0.110$  Inch, 7,700 Sq. Mils. Substrate (Die Backside) Is Connected to V+. Transistor Count, 290.

# 0P191/0P291/0P491–Typical Performance Characteristics



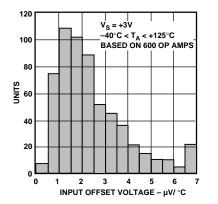


Figure 2. OP291 Input Offset Voltage Distribution,  $V_S = +3 V$ 

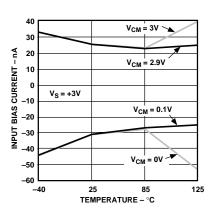


Figure 5. Input Bias Current vs. Temperature,  $V_S = +3 V$ 

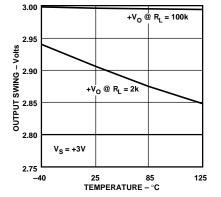


Figure 8. Output Voltage Swing vs. Temperature,  $V_S = +3 V$ 

Figure 3. OP291 Input Offset Voltage Drift Distribution,  $V_S = +3 V$ 

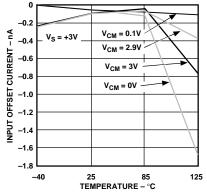


Figure 6. Input Offset Current vs. Temperature,  $V_s = +3 V$ 

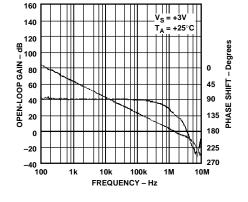


Figure 9. Open-Loop Gain & Phase vs. Frequency,  $V_{\rm S} = +3$  V

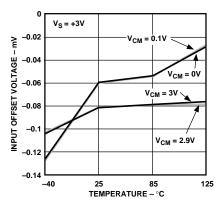


Figure 4. Input Offset Voltage vs. Temperature,  $V_S = +3 V$ 

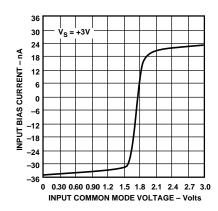


Figure 7. Input Bias Current vs. Common-Mode Voltage,  $V_S = +3 V$ 

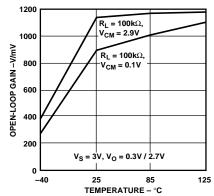


Figure 10. Open-Loop Gain vs. Temperature,  $V_S = +3 V$ 

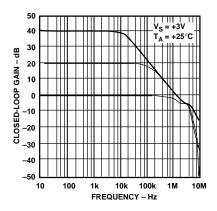


Figure 11. Closed-Loop Gain vs. Frequency,  $V_S = +3 V$ 

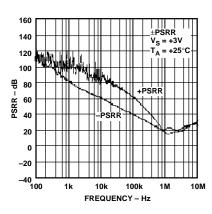


Figure 14. PSRR vs. Frequency,  $V_S = +3 V$ 

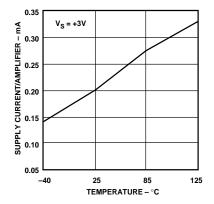


Figure 17. Supply Current vs. Temperature,  $V_S = +3 V$ , +5 V,  $\pm 5 V$ 

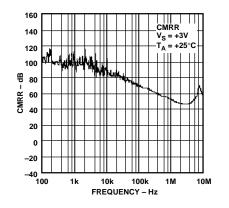


Figure 12. CMRR vs. Frequency,  $V_{\rm S} = +3 V$ 

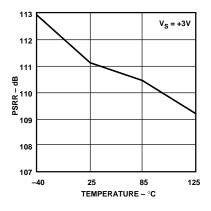


Figure 15. PSRR vs. Temperature,  $V_S = +3 V$ 

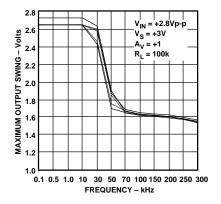


Figure 18. Maximum Output Swing vs. Frequency,  $V_S = +3 V$ 

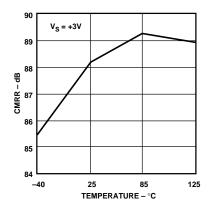


Figure 13. CMRR vs. Temperature,  $V_S = +3 V$ 

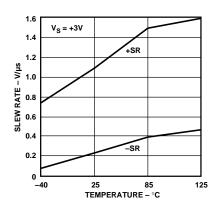


Figure 16. Slew Rate vs. Temperature,  $V_S = +3 V$ 

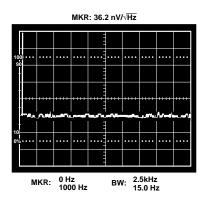


Figure 19. Voltage Noise Density,  $V_S = +3 V \text{ to } \pm 5 V$ ,  $A_{VO} = 1000$ 

## 0P191/0P291/0P491–Typical Performance Characteristics

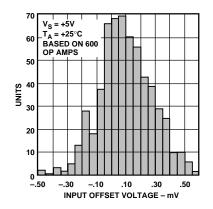


Figure 20. OP291 Input Offset Voltage Distribution,  $V_S = +5 V$ 

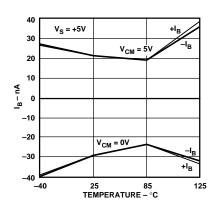


Figure 23. Input Bias Current vs. Temperature,  $V_S = +5 V$ 

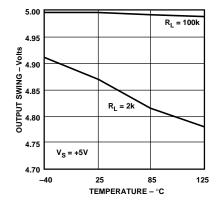


Figure 26. Output Voltage Swing vs. Temperature,  $V_{\rm S}$  = +5 V

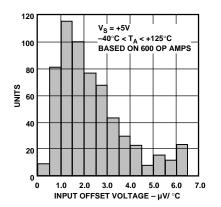


Figure 21. OP291 Input Offset Voltage Drift Distribution,  $V_s = +5 V$ 

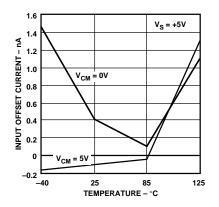


Figure 24. Input Offset Current vs. Temperature,  $V_{\rm S}$  = +5 V

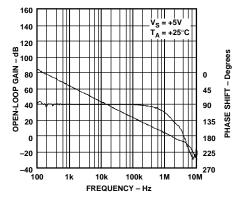


Figure 27. Open-Loop Gain & Phase vs. Frequency,  $V_{\rm S}$  = +5 V

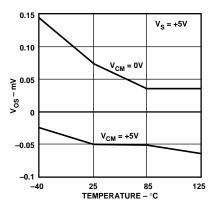


Figure 22. Input Offset Voltage vs. Temperature,  $V_s = +5 V$ 

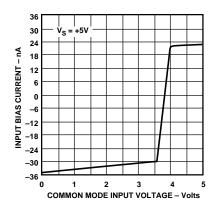


Figure 25. Input Bias Current vs. Common-Mode Voltage,  $V_S = +5 V$ 

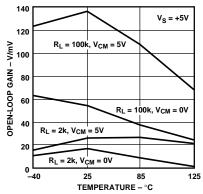
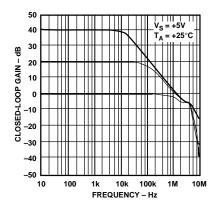


Figure 28. Open-Loop Gain vs. Temperature,  $V_{\rm S}$  = +5 V



160 CMRR 140 V<sub>S</sub> = +5V 120 +25°C 100 睱 80 CMRR -60 40 20 0 -20 -40 -100 100k 1k 10k 1M 10M FREQUENCY - Hz

Figure 29. Closed-Loop Gain vs. Frequency,  $V_S = +5 V$ 

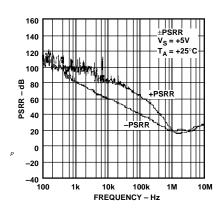


Figure 32. PSRR vs. Frequency,  $V_{\rm S} = +5 V$ 

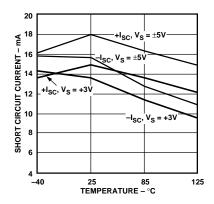


Figure 35. Short Circuit Current vs. Temperature,  $V_S = +3 V$ , +5 V,  $\pm 5 V$ 

Figure 30. CMRR vs. Frequency,  $V_S = +5 V$ 

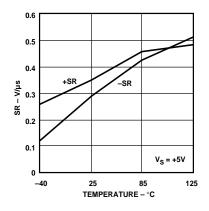


Figure 33. OP291 Slew Rate vs. Temperature,  $V_S = +5 V$ 

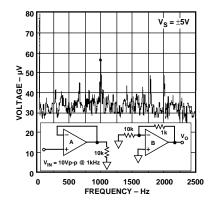


Figure 36. Channel Separation,  $V_S = \pm 5 V$ 

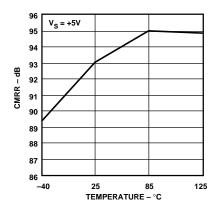


Figure 31. CMRR vs. Temperature,  $V_S = +5 V$ 

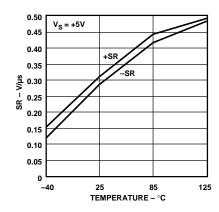


Figure 34. OP491 Slew Rate vs. Temperature,  $V_S = +5 V$ 

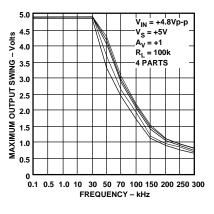


Figure 37. Maximum Output Swing vs. Frequency,  $V_{\rm S}$  = +5 V

# 0P191/0P291/0P491–Typical Performance Characteristics

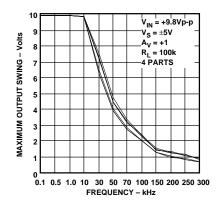


Figure 38. Maximum Output Swing vs. Frequency,  $V_S = \pm 5 V$ 

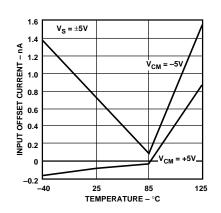


Figure 41. Input Offset Current vs. Temperature,  $V_s = \pm 5 V$ 

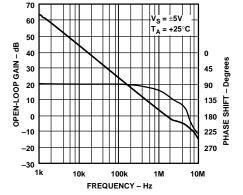


Figure 44. Open-Loop Gain & Phase vs. Frequency,  $V_{\rm S}$  = ±5 V

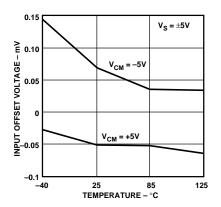


Figure 39. Input Offset Voltage vs. Temperature,  $V_S = \pm 5 V$ 

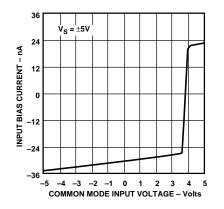


Figure 42. Input Bias Current vs. Common-Mode Voltage,  $V_S = \pm 5 V$ 

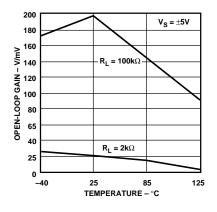


Figure 45. Open-Loop Gain vs. Temperature,  $V_{\rm S} = \pm 5 V$ 

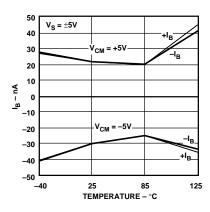


Figure 40. Input Bias Current vs. Temperature,  $V_S = \pm 5 V$ 

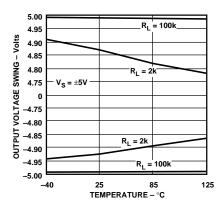


Figure 43. Output Voltage Swing vs. Temperature,  $V_S = \pm 5 V$ 

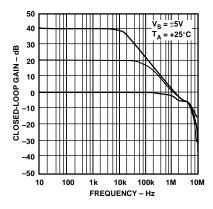
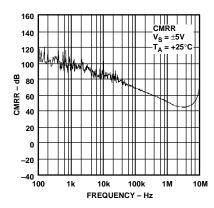


Figure 46. Closed-Loop Gain vs. Frequency,  $V_{\rm S}$  = ±5 V



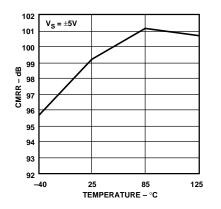


Figure 47. CMRR vs. Frequency,  $V_S = \pm 5 V$ 

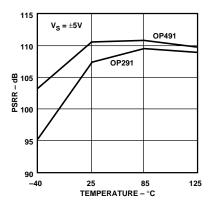
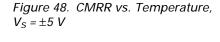


Figure 50. OP291/OP491 PSRR vs. Temperature,  $V_{\rm S}$  = ±5 V



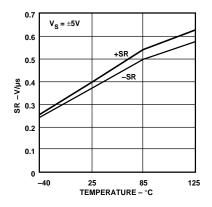
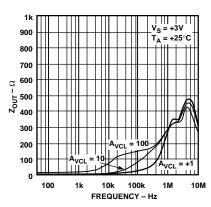


Figure 51. Slew Rate vs. Temperature,  $V_S = \pm 5 V$ 

160 140 +5V ٧s 120 +25°C 100 뜅 80 20 0 -20 -40 ┗ 100 1k 10k 100k 1M 10M FREQUENCY - Hz

Figure 49. PSRR vs. Frequency,  $V_{\rm S} = \pm 5 V$ 



*Figure 52. Output Impedance vs. Frequency* 

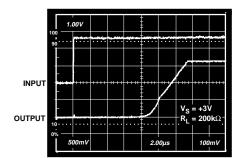


Figure 53. Large Signal Transient Response,  $V_S = +3 V$ 

Figure 54. Large Signal Transient Response,  $V_S = \pm 5 V$ 

#### FUNCTIONAL DESCRIPTION

The OP191/OP291/OP491 are single supply, micropower amplifiers featuring rail-to-rail inputs and outputs. In order to achieve wide input and output ranges, these amplifiers employ unique input and output stages. As the simplified schematic shows (Figure 55), the input stage is actually comprised of two differential pairs, a PNP pair and an NPN pair. These two stages do not actually work in parallel. Instead, only one or the other stage is on for any given input signal level. The PNP stage (transistors Q1 and Q2) is required to ensure that the amplifier remains in the linear region when the input voltage approaches and reaches the negative rail. On the other hand, the NPN stage (transistors Q5 and Q6) is needed for input voltages up to and including the positive rail.

For the majority of the input common-mode range, the PNP stage is active, as is evidenced by examining the graph of Input Bias Current vs. Common-Mode Voltage. Notice that the bias current switches direction at approximately 1.2 volts to 1.3 volts below the positive rail. At voltages below this, the bias current flows out of the OP291, indicating a PNP input stage. Above this voltage, however, the bias current enters the device, revealing the NPN stage. The actual mechanism within the amplifier for switching between the input stages is comprised of the transistors Q3, Q4, and Q7. As the input common-mode voltage increases, the emitters of Q1 and Q2 follow that voltage plus a diode drop. Eventually the emitters of Q1 and Q2 are high enough to turn Q3 on. This diverts the 8 µA of tail current away from the PNP input stage, turning it off. Instead, the current is mirrored through Q4 and Q7 to activate the NPN input stage.

Notice that the input stage includes  $5 \text{ k}\Omega$  series resistors and differential diodes, a common practice in bipolar amplifiers to protect the input transistors from large differential voltages. These diodes will turn on whenever the differential voltage

exceeds approximately 0.6 V. In this condition, current will flow between the input pins, limited only by the two 5 k $\Omega$  resistors. Being aware of this characteristic is important in circuits where the amplifier may be operated open-loop, such as a comparator. Evaluate each circuit carefully to make sure that the increase in current does not affect the performance.

The output stage of the OP191 family uses a PNP and an NPN transistor as do most output stages; however, the output transistors, Q32 and Q33, are actually connected with their collectors to the output pin to achieve the rail-to-rail output swing. As the output voltage approaches either the positive or negative rail, these transistors begin to saturate. Thus, the final limit on output voltage is the saturation voltage of these transistors, which is about 50 mV. The output stage does have inherent gain arising from the collectors and any external load impedance. Because of this, the open-loop gain of the amplifier is dependent on the load resistance.

#### **Input Overvoltage Protection**

As with any semiconductor device, whenever the condition exists for the input to exceed either supply voltage, attention needs to be paid to the input overvoltage characteristic. When an overvoltage occurs, the amplifier could be damaged depending on the voltage level and the magnitude of the fault current. Figure 56 shows the characteristic for the OP191 family. This graph was generated with the power supplies at ground and a curve tracer connected to the input. As can be seen, when the input voltage exceeds either supply by more than 0.6 V, internal pn-junctions energize allowing current to flow from the input to the supplies. As described above, the OP291/OP491 does have 5 k $\Omega$  resistors in series with each input, which helps limit the current. Calculating the slope of the current versus voltage in the graph confirms the 5 k $\Omega$  resistor.

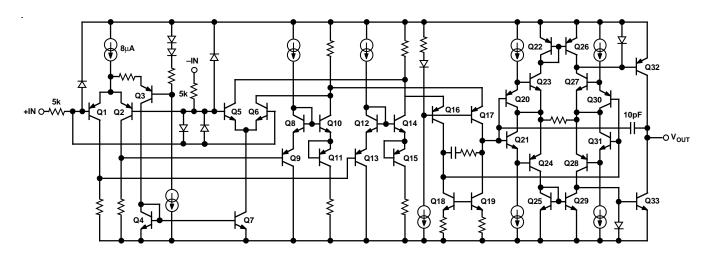


Figure 55. Simplified Schematic

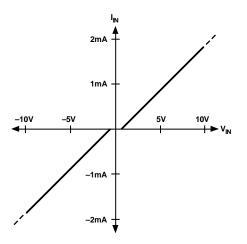


Figure 56. Input Overvoltage Characteristics

This input current is not inherently damaging to the device as long as it is limited to 5 mA or less. In the case shown, for an input of 10 V over the supply, the current is limited to 1.8 mA. If the voltage is large enough to cause more than 5 mA of current to flow, then an external series resistor should be added. The size of this resistor is calculated by dividing the maximum overvoltage by 5 mA and subtracting the internal 5 k $\Omega$  resistor. For example, if the input voltage could reach 100 V, the external resistor should be (100 V/5 mA) –5 k = 15 k $\Omega$ . This resistance should be placed in series with either or both inputs if they are subjected to the overvoltages. For more information on general overvoltage characteristics of amplifiers refer to the *1993 System Applications Guide*, available from the Analog Devices Literature Center.

#### **Output Voltage Phase Reversal**

Some operational amplifiers designed for single-supply operation exhibit an output voltage phase reversal when their inputs are driven beyond their useful common-mode range. Typically for single-supply bipolar op amps, the negative supply determines the lower limit of their common-mode range. With these devices, external clamping diodes, with the anode connected to ground and the cathode to the inputs, prevent input signal excursions from exceeding the device's negative supply (i.e., GND), preventing a condition which could cause the output voltage to change phase. JFET-input amplifiers may also exhibit phase reversal, and, if so, a series input resistor is usually required to prevent it.

The OP191 family is free from reasonable input voltage range restrictions due to its novel input structure. In fact, the input signal can exceed the supply voltage by a significant amount without causing damage to the device. As illustrated in Figure 57, the OP191 family can safely handle a 20 V p-p input signal on  $\pm 5$  V supplies without exhibiting any sign of output voltage phase reversal or other anomalous behavior. Thus no external clamping diodes are required.

#### **Overdrive Recovery**

The overdrive recovery time of an operational amplifier is the time required for the output voltage to recover to its linear region from a saturated condition. This recovery time is important in applications where the amplifier must recover quickly after a large transient event, such as a comparator. The circuit shown in Figure 58 was used to evaluate the OP191 family's overload recovery time. The OP191 family takes approximately 8  $\mu$ s to recover from positive saturation and approximately 6.5  $\mu$ s to recover from negative saturation.

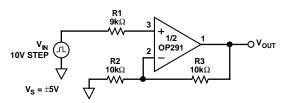


Figure 58. Overdrive Recovery Time Test Circuit

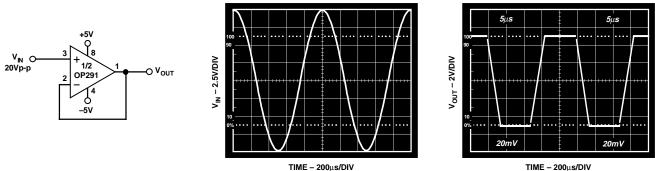


Figure 57. Output Voltage Phase Reversal Behavior

#### APPLICATIONS

#### Single +3 V Supply, Instrumentation Amplifier

The OP291's low supply current and low voltage operation make it ideal for battery powered applications such as the instrumentation amplifier shown in Figure 59. The circuit utilizes the classic two op amp instrumentation amplifier topology, with four resistors to set the gain. The equation is simply that of a noninverting amplifier as shown in the figure. The two resistors labeled R1 should be closely matched to each other as well as both resistors labeled R2 to ensure good common-mode rejection performance. Resistor networks ensure the closest matching as well as matched drifts for good temperature stability. Capacitor C1 is included to limit the bandwidth and, therefore, the noise in sensitive applications. The value of this capacitor should be adjusted depending on the desired closed-loop bandwidth of the instrumentation amplifier. The RC combination creates a pole at a frequency equal to  $1/(2 \pi \times R1C1)$ . If AC-CMRR is critical, than a matched capacitor to C1 should be included across the second resistor labeled R1.

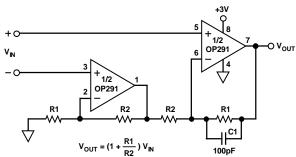


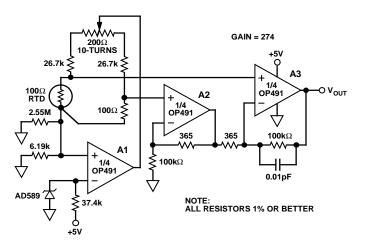
Figure 59. Single +3 V Supply Instrumentation Amplifier

Because the OP291 accepts rail-to-rail inputs, the input common-mode range includes both ground and the positive supply of 3 V. Furthermore, the rail-to-rail output range ensures the widest signal range possible and maximizes the dynamic range of the system. Also, with its low supply current of  $300 \ \mu$ A/device, this circuit consumes a quiescent current of only  $600 \ \mu$ A, yet still exhibits a gain bandwidth of 3 MHz.

A question may arise about other instrumentation amplifier topologies for single supply applications. For example, a variation on this topology adds a fifth resistor between the two inverting inputs of the op amps for gain setting. While that topology works well in dual supply applications, it is inherently not appropriate for single supply circuits. The same could be said for the traditional three op amp instrumentation amplifier. In both cases, the circuits simply will not work in single supply situations unless a false ground between the supplies is created.

#### **Single Supply RTD Amplifier**

The circuit in Figure 60 uses three op amps of the OP491 to develop a bridge configuration for an RTD amplifier that operates from a single +5 V supply. The circuit takes advantage of the OP491's wide output swing range to generate a high bridge excitation voltage of 3.9 V. In fact, because of the railto-rail output swing, this circuit will work with supplies as low as 4.0 V. Amplifier A1 servos the bridge to create a constant excitation current in conjunction with the AD589, a 1.235 V precision reference. The op amp maintains the reference voltage across the parallel combination of the 6.19 k $\Omega$  and 2.55 M $\Omega$  resistor, which generates a 200  $\mu$ A current source. This current splits evenly and flows through both halves of the bridge. Thus, 100 µA flows through the RTD to generate an output voltage based on its resistance. A 3-wire RTD is used to balance the line resistance in both 100  $\Omega$  legs of the bridge to improve accuracy.



#### Figure 60. Single Supply RTD Amplifier

Amplifiers A2 and A3 are configured in the two op amp IA discussed above. Their resistors are chosen to produce a gain of 274, such that each 1°C increase in temperature results in a 10 mV change in the output voltage, for ease of measurement. A 0.01  $\mu F$  capacitor is included in parallel with the 100 k $\Omega$  resistor on amplifier A3 to filter out any unwanted noise from this high gain circuit. This particular RC combination creates a pole at 1.6 kHz.

#### A +2.5 V Reference from a +3 V Supply

In many single-supply applications, the need for a 2.5 V reference often arises. Many commercially available monolithic 2.5 V references require at least a minimum operating supply voltage of 4 V. The problem is exacerbated when the minimum operating system supply voltage is + 3 V. The circuit illustrated in Figure 61 is an example of a +2.5 V that operates from a single +3 V supply. The circuit takes advantage of the OP291's rail-to-rail input and output voltage ranges to amplify an AD589's 1.235 V output to +2.5 V. The OP291's low TCV<sub>OS</sub> of 1  $\mu$ V/°C helps to maintain an output voltage temperature coefficient of less than 200 ppm/°C. The circuit's overall temperature coefficient. Lower tempco resistors are recommended. The entire circuit draws less than 420  $\mu$ A from a +3 V supply at +25°C.

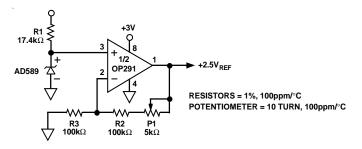


Figure 61. A +2.5 V Reference that Operates on a Single +3 V Supply

#### +5 V Only, 12-Bit DAC Swings Rail-to-Rail

The OP191 family is ideal for use with a CMOS DAC to generate a digitally controlled voltage with a wide output range. Figure 62 shows the DAC8043 used in conjunction with the AD589 to generate a voltage output from 0 V to 1.23 V The DAC is actually operated in "voltage switching" mode where the reference is connected to the current output,  $I_{OUT}$ , and the output voltage is taken from the  $V_{REF}$  pin. This topology is inherently noninverting as opposed to the classic current output mode, which is inverting and, therefore, unsuitable for single supply.

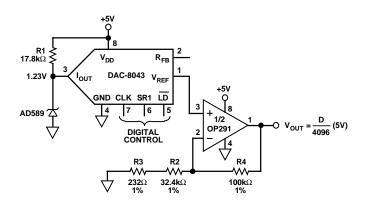


Figure 62. +5 V Only, 12-Bit DAC Swings Rail-to-Rail

The OP291 serves two functions. First, it is required to buffer the high output impedance of the DAC's  $V_{REF}$  pin, which is on the order of 10 k $\Omega$ . The op amp provides a low impedance output to drive any following circuitry. Secondly, the op amp amplifies the output signal to provide a rail-to-rail output swing. In this particular case, the gain is set to 4.1 to generate a 5.0 V output when the DAC is at full scale. If other output voltage ranges are needed, such as 0 to 4.095, the gain can easily be adjusted by altering the value of the resistors.

#### **A High Side Current Monitor**

In the design of power supply control circuits, a great deal of design effort is focused on ensuring a pass transistor's long-term reliability over a wide range of load current conditions. As a result, monitoring and limiting device power dissipation is of prime importance in these designs. The circuit illustrated in Figure 63 is an example of a + 5 V, single-supply high side current monitor that can be incorporated into the design of a voltage regulator with fold-back current limiting or a high current power supply with crowbar protection. This design uses an OP291's rail-to-rail input voltage range to sense the voltage drop across a 0.1  $\Omega$  current shunt. A p-channel MOSFET used as the feedback element in the circuit converts the op amp's differential input voltage into a current. This current is then applied to R2 to generate a voltage that is a linear representation of the load current. The transfer equation for the current monitor is given by:

Monitor Output = 
$$R2 \times \left(\frac{R_{SENSE}}{R_1}\right) \times I_L$$

For the element values shown, the Monitor Output's transfer characteristic is 2.5 V/A.

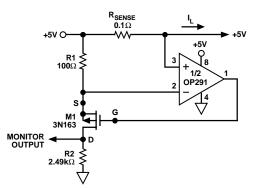
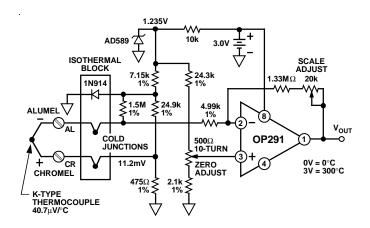


Figure 63. A High-Side Load Current Monitor

#### A +3 V, Cold Junction Compensated Thermocouple Amplifier

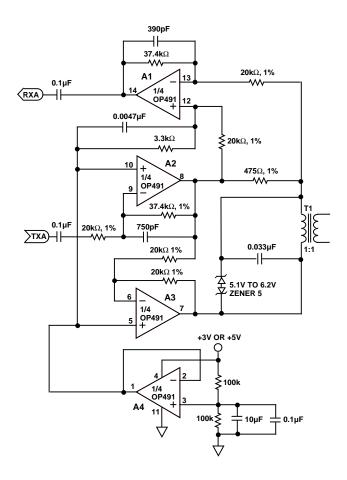
The OP291's low supply operation makes it ideal for +3 V battery powered applications such as the thermocouple amplifier shown in Figure 64. The K-type thermocouple terminates in an isothermal block where the junctions' ambient temperature is continuously monitored using a simple 1N914 diode. The diode corrects the thermal EMF generated in the junctions by feeding a small voltage, scaled by the 1.5 M $\Omega$  and 475  $\Omega$  resistors, to the op amp.

To calibrate this circuit, immerse the thermocouple measuring junction in a 0°C ice bath, and adjust the 500  $\Omega$  pot to zero volts out. Next, immerse the thermocouple in a 250°C temperature bath or oven and adjust the Scale Adjust pot for an output voltage of 2.50 V. Within this temperature range, the K-type thermocouple is accurate to within  $\pm 3$ °C without linearization.



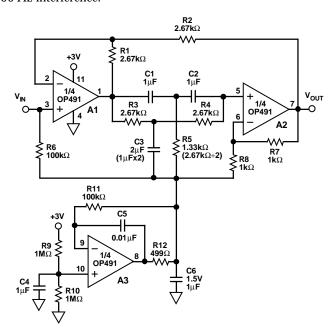
#### Figure 64. A 3 V, Cold Junction Compensated Thermocouple Amplifier

#### **Single Supply, Direct Access Arrangement for Modems** An important building block in modems is the telephone line interface. In the circuit shown in Figure 65, a direct access arrangement is utilized for transmitting and receiving data from the telephone line. Amplifier A1 is the receiving amplifier, and amplifiers A2 and A3 are the transmitters. The forth amplifier, A4, generates a pseudo ground half way between the supply voltage and ground. This pseudo ground is needed for the ac coupled bipolar input signals.



# Figure 65. Single Supply Direct Access Arrangement for Modems

The transmit signal, TXA, is inverted by A2 and then reinverted by A3 to provide a differential drive to the transformer, where each amplifier supplies half the drive signal. This is needed because of the smaller swings associated with a single supply as opposed to a dual supply. Amplifier A1 provides some gain for the received signal, and it also removes the transmit signal present at the transformer from the receive signal. To do this, the drive signal from A2 is also fed to the noninverting input of A1 to cancel the transmit signal from the transformer. The OP491's bandwidth of 3 MHz and rail-to-rail output swings ensures that it can provide the largest possible drive to the transformer at the frequency of transmission. A +3 V, 50 Hz/60 Hz Active Notch Filter with False Ground To process ac signals in a single-supply system, it is often best to use a false-ground biasing scheme. A circuit that uses this approach is illustrated in Figure 66. In this circuit, a falseground circuit biases an active notch filter used to reject 50 Hz/ 60 Hz power line interference in portable patient monitoring equipment. Notch filters are quite commonly used to reject power line frequency interference which often obscures low frequency physiological signals, such as heart rates, blood pressure readings, EEGs, EKGs, etcetera. This notch filter effectively squelches 60 Hz pickup at a filter Q of 0.75. Substituting 3.16 k $\Omega$  resistors for the 2.67 k $\Omega$  resistors in the twin-T section (R1 through R5) configures the active filter to reject 50 Hz interference.



#### Figure 66. A +3 V Single-Supply, 50 Hz/60 Hz Active Notch Filter with False Ground

Amplifier A3 is the heart of the false-ground bias circuit. It simply buffers the voltage developed by R9 and R10 and is the reference for the active notch filter. Since the OP491 exhibits a rail-to-rail input common-mode range, R9 and R10 are chosen to split the +3 V supply symmetrically. An in-the-loop compensation scheme is used around the OP491 that allows the op amp to drive C6, a 1  $\mu$ F capacitor, without oscillation. C6 maintains a low impedance ac ground over the operating frequency range of the filter.

The filter section uses a pair of OP491s in a twin-T configuration whose frequency selectivity is very sensitive to the relative matching of the capacitors and resistors in the twin-T section. Mylar is the material of choice for the capacitors, and the relative matching of the capacitors and resistors determines the filter's passband symmetry. Using 1% resistors and 5% capacitors produces satisfactory results.

#### Single-Supply Half-Wave and Full-Wave Rectifiers

An OP191 family configured as a voltage follower operating on a single supply can be used as a simple half-wave rectifier in low-frequency (<2 kHz) applications. A full-wave rectifier can be configured with a pair of OP291s as illustrated in Figure 67. The circuit works in the following way: When the input signal is above 0 V, the output of amplifier A1 follows the input signal. Since the noninverting input of amplifier A2 is connected to A1's output, op amp loop control forces the A2's inverting input to the same potential. The result is that both terminals of R1 are equipotential; i.e., no current flows. Since there is no current flow in R1, the same condition exists upon R2; thus, the output of the circuit tracks the input signal. When the input signal is below 0 V, the output voltage of A1 is forced to 0 V. This condition now forces A2 to operate as an inverting voltage follower because the noninverting terminal of A2 is at 0 V as well. The output voltage at V<sub>OUT</sub>A is then a full-wave rectified version of the input signal. If needed, a buffered, half-wave rectified version of the input signal is available at  $V_{OUT}B$ .

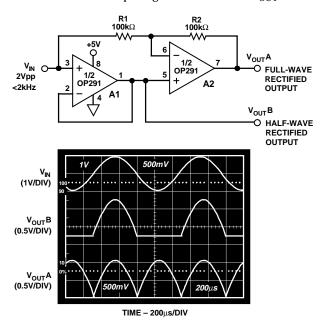


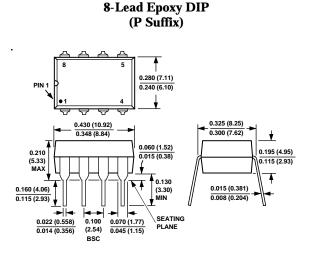
Figure 67. Single-Supply Half-Wave and Full-Wave Rectifiers Using an OP291

* OP491 SPICE N * *	Macro-model Rev. A, 5/94 ARG/ADI	* * POLE AT 2.5 MHz *			
* Copyright 1994	by Analog Devices	G3 98 18 (12,39) 1E-6			
*		R11 18 98 1E6			
	ME.DOC" file for License Statement. Use of	C4 18 98 63.662E-15 *			
* visions in the Lie	ates your acceptance of the terms and pro- cense Statement.	* * BIAS CURRENT-VS-COMMON-MODE VOLTAGE *			
* Node assignmen	ts	EP 97 0 (99,0) 1			
*	noninverting input	VB 99 17 1.3			
*	inverting input	RB 17 50 1E9			
*	positive supply	E3 19 0 (15,17) 16			
*	negative supply	D13 19 20 DX R12 20 0 1E6			
*	output	G4 98 21 (20,0) 1E-3			
.SUBCKT OP491		R13 21 98 5E3			
*		D14 21 22 DY			
* INPUT STAGE *	1	E4 97 22 (POLY(1) (99,98) -0.765 1 *			
ř I1 99 7	8.06E-6	* POLE AT 100 MHz			
Q1 6 4	7 QP	*			
Q2 5 3	7 QP	G6 98 40 (18,39) 1E-6			
D1 3 99	DX	R20 40 98 1E6			
D2 4 99	DX	C10 40 98 1.592E-15 *			
D3 3 4 D4 4 3	DX DX	* OUTPUT STAGE			
R1 3 8	5E3	*			
R2 4 2	5E3	RS1 99 39 109.375E3			
R3 5 50	6.4654E3	RS2 39 50 109.375E3			
R4 6 50	6.4654E3	RO1 99 45 41.667			
EOS 8 1	POLY(1) (16,39) -0.08E-3 1	RO2 45 50 41.667			
IOS 3 4	50E-12	G7 45 99 (99,40) 24E-3			
GB1 3 98	(21,98) 50E-9 (21,98) 50E 9	G8 50 45 (40,50) 24E-3			
GB2 4 98 CIN 1 2	(21,98) 50E-9 1E-12	G9 98 60 (45,40) 24E-3 D9 60 61 DX			
*	11-12	D10 62 60 DX			
* 1ST GAIN STA	GE	V7 61 98 DC 0			
*		V8 98 62 DC 0			
EREF 98 0	(39,0) 1	FSY 99 50 POLY(2) V7 V8 0.207E-3 1 1			
G1 98 9	(6,5) 31.667E-6	D11 41 45 DZ			
R7 9 98	1E6	D12 45 42 DZ			
EC1 99 10	POLY(1) (99,39) -0.52 1 POLY(1) (39,50) -0.52 1	V5 40 41 0.131 V6 42 40 0.131			
EC2 11 50 D5 9 10	POLY(1) (39,50) -0.52 1 DX	V6 42 40 0.131 .MODEL DX D()			
D6 11 9	DX	.MODEL DY D(IS=1E-9)			
*		.MODEL DZ D $(IS=1E-6)$			
* 2ND GAIN STA *	AGE AND DOMINANT POLE AT 1.25 Hz	.MODEL QP PNP(BF=66.667) .ENDS			
G2 98 12	(9,39) 8E-6				
R8 12 98	276.311E6				
C2 12 98	16E-12				
D7 12 13	DX				
D8 14 12	DX 0.58				
V1 99 13 V2 14 50	0.58 0.58				
vz 14 50 *	0.00				
* COMMON-MC	DDE STAGE				
ECM 15 98	POLY(2) (1,39) (2,39) 0 0.5 0.5				
R9 15 16	1E6				
R10 16 98	10				

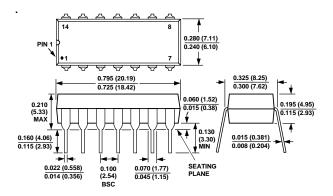
### OP191/OP291/OP491

#### **OUTLINE DIMENSIONS**

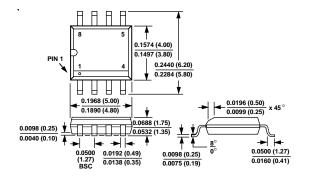
Dimensions shown in inches and (mm).



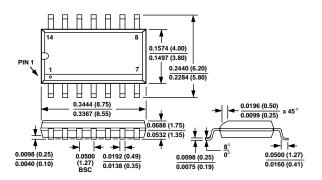
#### 14-Lead Epoxy DIP (P Suffix)



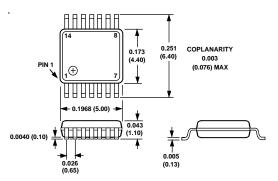
#### 8-Lead Narrow-Body SO (S Suffix)



14-Lead Narrow-Body SO (S Suffix)



14-Lead TSSOP (RU Suffix)



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